

Method Statement

TGL Tripod Recovery Subsea Tripod Cutting

Prepared for:



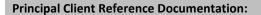
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Document Title:

LSK-TGL02-OP3-MS01-R01 - Subsea Tripod Cutting

























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1 INTRODUCTION

1.1 Project Overview

Leask Marine Ltd has been involved in the engineering and operations of Tidal Generation Ltd (TGL) Tripod at European Marine Energy Centre (EMEC) Tidal Test Site, in Orkney Isles. In 2006, the Tripod was drilled, piled and grouted to the seabed at Berth 2 in Fall of Warness.



Figure 1 – Photo of TGL Foundation Pre & Thru-Deployment

EMEC has contracted Leask Marine to recover the tripod, developing the methodology and procedures. The Tripod need to be disconnected from the seabed, transported, cut into small pieces and then recycled.

The project is divided in four phases:

- 1. Pile cutting at Seabed
- 2. Lifting and Towing
- 3. Cutting into section at location nearshore Eday
- 4. Onshore cutting and disposal of Steel & Grout

1.2 Document Objective

This document outlines the methodology that Leask Marine will adopt for the execution of Phase 3 of the decommissioning project whereby the tripod will be cut into manageable sections by divers at an inshore location

1.3 References

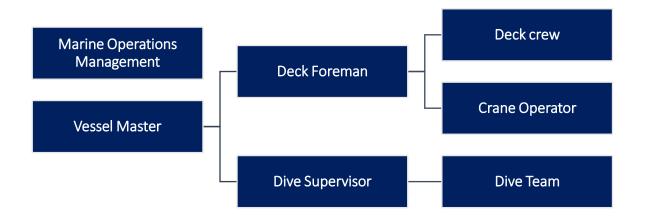
All References and information contained in this document is related to information provided by the Client / Contractor:

1. FT-001 - Tripod Areas of Interest - Blackfish - 28/11/17



2 OPERATION PARTICULARS

2.1 Operation Structure





2.2 Interfaces & Contacts

Client	EMEC
Marine Contractor	Leask Marine Ltd.

Client - EMEC

TITLE	NAME	TELEPHONE	MOBILE
Project Manager	Andy Shanks	+44 (0) 1856 852 001	+44(0) 7961 551 201
Operations &	John Skuse	+44 (0) 1856 852 205	+44(0) 7972 033 137
Maintenance Manager			
Operation Engineer	Donald Sinclair	-	+44(0) 7789 698 144
Duty Manager	-	-	+44(0) 7624 345 411

Leask Marine

TITLE	NAME	TELEPHONE	MOBILE
Director	Douglas Leask	+44 (0) 1856 874 725	+44 (0) 7889 651 680
Operation Manager	Oliver Bethwaite	+44 (0) 1856 874 725	+44 (0) 7966 228 830
Commercial Manager	John Macleod	+44 (0) 1856 874 725	-
C-Odyssey	-	-	+44 (0) 7718 424 491

2.3 Communications

Internal Communications will be carried out by VHF and UHF radio with the following channels:

- Emergency Channel VHF Channel 16
- Leask Marine VHF Channel 74
- VTS VHF Channel 11
- Harbours VHF Channel 14



3 SITE & WEATHER

3.1 Site Details

Upon the commencement of this operation the TGL tripod will have been recovered from the seabed at Berth 2 of the Falls of Warness Tidal Test Site and wet-stored at a location nearshore Eday; the water depth at this location is approximately 20m



Figure 2 – Nearshore Eday (Orkney Islands)

The area allocated for the tripod cutting operation is outlined by the coordinates in Table 1

	Lat	Long	Easting	Northing
Corner 1	059° 9.696′N	002° 48.329′ W	511123	6558062
Corner 2	059° 9.671′ N	002° 48.093′ W	511348	6558017
Corner 3	059° 9.302′ N	002° 48.244′ W	511206	6557332
Corner 4	059° 9.329′ N	002° 48.244′ W	510966	6557381

Table 1 – Decommissioning Area

3.2 Site Controls

Suitable site controls will be put in place which will include but may not be limited to:

- Risk assessment
- Tool box talks
- Ensure all emergency equipment on site is ready for use
- Any additional hazards to be identified and added to change of records form
- Ensure permit to work system is in place
- Sea Swell to be monitored at all times
- Tide to be monitored at all times
- Surface conditions to be monitored at all times
- Leask Marine Permit to work system signed off by client



3.3 Project Hazard Identification

- Sea Swell
- Vessel Moorings (stability)
- Tide
- Moving Machinery
- Underwater Crane / Winch Movements
- Heavy Loads (pinch points)
- Structure Stability

All items listed above will have appropriate Risk Assessments which are located in the Risk Assessment document.

3.4 Weather & Current

- Dive supervisor and vessel skipper to agree on decisions if conditions are unsafe and not suitable for operations.
- Wave height is less than 1.5 Meters Maximum
- Wind speed is less than 10 knots
- Dive Supervisor and vessel skipper to monitor at all times.
- (Designated communication VHF channel 74 to be kept clear during diving operations)
- Dive working parameters as stated below:

		Current (Knots)				
Dive Method	0-0.5	0.5-0.8	0.8-1.0	1.0-1.2	1.2-1.5	Over 1.5
Surface supply - Mid water	(1)	(2)	(3) + (4)		(4)	•
Surface supply - Bottom	(1)	(1) + (2)	(2) + (3)	(3) (4)		
Basket / Bell - Mid water	(1) (1) + (2) (3) (4)			4)		
Basket / Bell - Bottom	((1)	(1) + (2)) (3) (4)		
Description: (1) Suitable	for workii	ng with loca	l factors ta	ken into a	account.	
(2) Some res	strictions v	will apply, o	bservatior	should b	e workabl	e.
(3) Probably	obably unsuitable, but local factors may permit.					
	ble without cofferdam protection					

Source - ADC-CoP: 001 - 7.6

The weather limits are:

OPERATION	Sign. Wave Height	Wind Speed	Tidal Current
Vessel Operation	< 2.0 meters	<20 knots	-
Lifting Operation	< 1.0 meters	<10 knots	< 2.0 knots
Diving Operation	< 1.0 meters	=	< 1.0 knots
Towing Operation	< 1.5 meters	<20 knots	< 5.0 knots

Vessel Master to monitor the weather condition all the times and make decision if site conditions are safe for operations and for personnel operating.



3.5 Access & Site Environment

All work sites are controlled for the duration of the operation:

- Secure site All Leask Marine personnel to sign in/out
- Leask Marine permit to work required
- Works to be carried out from Vessel
- Crane / Man basket available if required

	Daily Operations Meeting	Signed
HOLD	Vessel Master / Project Operations Manager to confirm all vessel movements with other site parties and ensure all notifications are in place	Date/



3.6 EMEC Requirements

Entry to site is strictly according to EMEC requirements, principally, but not exclusively:

- EMEC SOP-003 Permit to Access Sit (Reference 13)
- EMEC SOP-063-07-02 Maritime Safety Information (Reference 18)
- EMEC REQUIREMENTS PRE-ENTRY:

Permit in Place from EMEC for site access and installation works

• EMEC REQUIREMENTS – ENTRY:

Upon crossing over into the site, as indicated by the Admiralty chart line, the EMEC Duty Officer should be notified via text message to 07624 345 411, the following:

- Name of Submitter
- Name of Vessel
- Time on Site
- Persons on Board
- Permit Number

• EMEC REQUIREMENTS - EXIT

Upon crossing over out of the site, as indicated by the Admiralty chart line, the EMEC Duty Officer should be notified via text message to 07624 345 411, the following:

- Name of Submitter
- Name of Vessel
- Time on Site
- Persons on Board
- Permit Number

• EMEC REQUIREMENTS – RE-ENTRY:

If at any time the vessel leaves site for any duration the same entry protocol must be followed



3.7 Permits / Notification

CONFIRMATION OF PERMIT TO WORK

HOLD	Permit Number Permit Holder Company Date Valid from Date expiry	
HOLD	All personnel onsite notified of operations	Supervisor
HOLD	Communications check Crane Operator / Banksman (VHF 74) Vessel Master (VHF 74) Dive Supervisor (VHF 74)	Supervisor Date
HOLD	Vessel Moorings secure/stable Ready for Diving Operations	Supervisor Date// Time



4 QHSE

4.1 Manual Handling

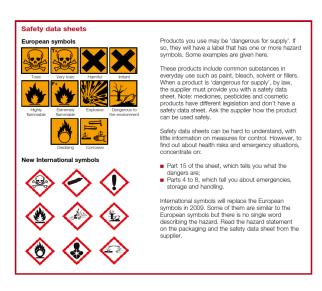
- Avoid hazardous manual handling operations so far as is reasonably practicable, for example by redesigning the task to avoid moving the load or by automating or mechanising the process.
- Make a suitable and sufficient assessment of any hazardous manual handling operations that cannot be avoided.





- Reduce the risk of injury from those operations so far as is reasonably practicable.
 Where possible, use mechanical assistance. Where this is not reasonably practicable, look at ways of changing the task, the load and working environment.
- Any amendments please add to change of records form found in this Method statement.
- For additional information please refer to the company handbook or the HSE website (www.hse.gov.uk)

4.2 COSHH



- Safety data sheets will be provided with any substance in use.
- For additional information please refer to company handbook or the HSE website (www.hse.gov.uk)



4.3 PPE Requirement

- Relevant PPE to be worn at all times.
- Additional PPE will be provided depending upon the activity being undertaken.











Leask Marine Ltd minimum requirement when working:

- Hard Hat
- Safety Glasses (weather / task dependent)
- Safety Gloves
- Life Vest / Coat / Jacket
- Safety clothing
- Rigger Boots



4.4 HSE Medical & First Aid Equipment

Equipment	Location
Mobile O2 Administration Kit	Dive Unit
First Aid Kit	Vessel Galley
Burns Kit	Vessel Galley
Eye Wash Kit	Vessel Galley

4.5 Personnel Qualifications

- Full equipment and vessel certification pack is available
- Senior Personnel CV's are made available on request



5 DIVING PARTICULARS

5.1 Diving Tables

- United States Navy dive tables Rev 7
- Company Procedure +1 safety margin on selected table for working depth.

5.2 Diving Team Size

Dive Team 5 Personnel:

- Dive Supervisor
- Diver 1
- Standby Diver
- + 1 Extra Diver
- Tender

Minimum team size 5 personnel. Team size maybe increased, or divers exchanged depending on job requirements. Dive supervisor to amend as required.

5.3 Diver Supervisor

- A standby diver will always be available at immediate readiness to provide any necessary assistance to the diver, whenever a diver is in the water, as instructed by the supervisor.
- The standby diver shall be fully dressed to enter the water, but does not need to be wearing the mask or helmet, but this does need to be fully operational and be immediately to hand, i.e. connected to the bail out and harness, properly tested and held by the diver or supported at or close to chest height.
- Where there are two working divers in the water at any one time, there must be a standby diver available on the surface for each pair of divers, to render assistance as instructed by the Supervisor.



5.4 Helmets

 Diver 1
 KM 27 SL

 Diver 2
 KM 27 SL

 S/Diver
 KM 28

 Spare
 KM 27 SL

5.5 Decompression Arrangements

Emergency Time response Breakdown:

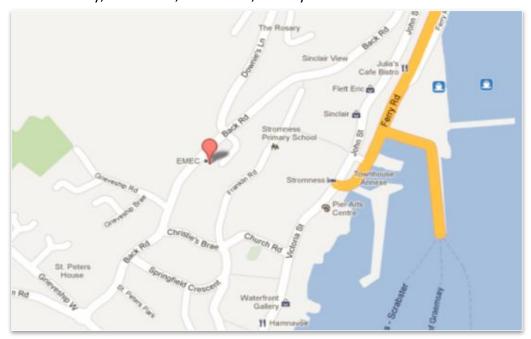
Emergency Response Transport

IN WATER DCI

Total Time Frame P	lan 1	15	Minutes
Casualty transferred to Stromness Facility			Minutes
Ambulance waiting at Stromness Pier, transfer time (or company van)			Minutes
On-site Vessel Heading to Stromness			Minutes
Coast Guard Notified	5	5	Minutes
Incident on-site casualty recovered / Stable			Minutes
On-site	()	Minutes

Stromness Hyperbaric Facility Location

Old Academy, Back Road, Stromness, Orkney





5.6 Suitability of Air Supply

Diver 1

- 3 x 50 litre cylinders 232 Bar (Primary) (21%)
- 1 x 50 litre cylinder 232 Bar (Secondary) (21%)
- 1 x 50 litre cylinder 232 Bar (Emergency) (21%)
- Bailout Cylinder 12 litre (Emergency 2) (21%)

Diver 2

- 1 x 50 litre cylinders 232 Bar (Primary) (21%)
- 1 x 50 litre cylinder 232 Bar (Secondary) (21%)
- 1 x 50 litre cylinder 232 Bar (Emergency) (21%)
- Bailout Cylinder 12 litre (Emergency 2) (21%)

Standby Diver

- 1 x 50 litre cylinders 232 Bar (Primary) (21%)
- 1 x 50 litre cylinder 232 Bar (Secondary) (21%)
- Bailout Cylinder 12 litre (Emergency 2) (21%)

5.7 Diver Launch & Recovery

- Primary Dive ladder for access and egress (Maximum height 1.5 meters)
- Secondary Crane available in emergency.
- Emergency Harness located on-board vessels.



Letter of Appointment of Diving Supervisors 5.8



C LEASK MARINE

January 1, 2018

To whom it may concern

Appointment of Diving Supervisor

In accordance with the Diving Operations at Work Regulations 1997 – Regulation 9 (1), 9(2) And Regulation 10(1), (9) (I)

Is appointed to act as Diving Supervisor for Diving Projects conducted by Leask Marine.

D Leash

Managing Director

January 1, 2018

To whom it may concern

Appointment of Diving Supervisor

In accordance with the Diving Operations at Work Regulations 1997 – Regulation 9(1), 9(2) And Regulation 10(1), (9)(i)

Is appointed to act as Diving Supervisor for Diving Projects conducted by Leask Marine.

Yours faithfully,

D Leash

Douglas Leask

Making Marine Renewables Work
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6 VESSELS & EQUIPMENT

6.1 Main Vessel

The vessel proposed for the operation is the MV C-Odyssey.



MV C-Odyssey







Specifications

Type of vessel	Multiw
Year built	2011
Category	MCA (
	Up to 1
	(from s
Passengers	12 plus
Flag state	UK
Port of registry	Kirkwa
MMSI No.	23508
IMO No.	983630
Call Sign	2ETW
Official Number	91798
Dissourcione	

Dimensions	
NAME OF TAXABLE PARTY.	20-
ength Beam	26m 10.5m
Deoth	3.5m
Draught	2.5m
Air draught – mast up	13.8m
Air draught – mast down	8.2m
Gross tonnage	150t
ree Deck Space	120m²
rec Dear Opasse	120011

Deck Equipme	est.	
Towing winch		60 t
Anchor handling		60 t
(Combined lift)		120 t
Tugger winch	3 x	15 t
Towing hook	SWL	25 t
Capstan		5t
Bow roller	5m SWL	120 t
Aft roller	3m SWL	60 t
Deck carrying cap		100 t
Deck crane	Hs 185t/m 5530kg @	
Deck crane (aft)	Hs 60Vm 4630kg @	10m

Pins SWL	50 t
Design load	105 t
Hub	400 mm
Stopper SWL	75 t
Design load	150 t
Hub	400 mm

Tank Capabilities Fuel/oil	100m²
Black/grey water Fresh water	9m² 45m²
Dirty oil	0.9m*
Ballast water	88m²
Accommodation Cabins 2	off twin berth

arge mess room Galley and laundry Generators

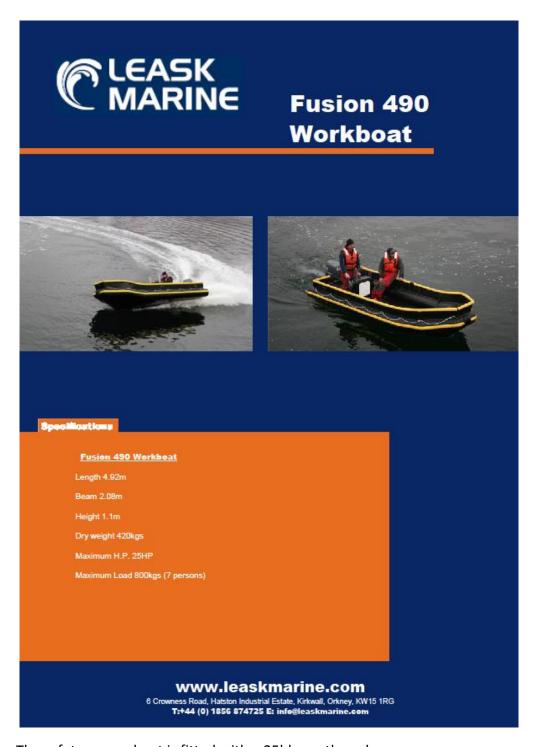
1 off 78 KVA 1 off 35 KVA K.W. 1790

engines 2 x caterpillar C32
power 2,400 bip at 1,800 rp
ulsion 2x fixed pitch propella
Nozzles 1,500mm

llard pull eed



6.2 Line Boat



- The safety rescue boat is fitted with a 25bhp outboard
- The safety rescue boat will be in a constant state of readiness when the MV C-Odyssey is moored onsite, a designated operator and crew man will be assigned during the TBT.
- The vessels aft crane is used to launch and recover the emergency recovery vessel.



6.3 Crane Specification

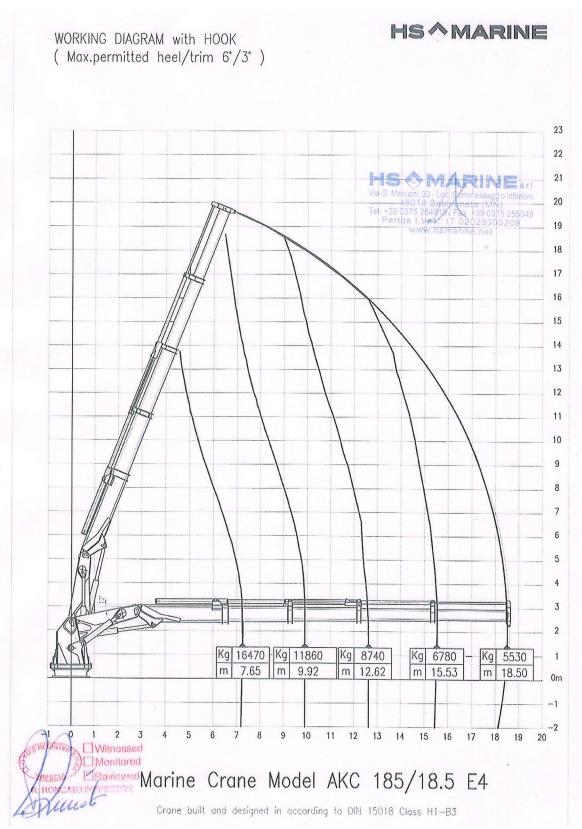


Figure 3 – Crane Specification



6.4 **Mooring and Vessel Positions**

The C-Odyssey will set-up on a 3-point mooring throughout pile cutting activities

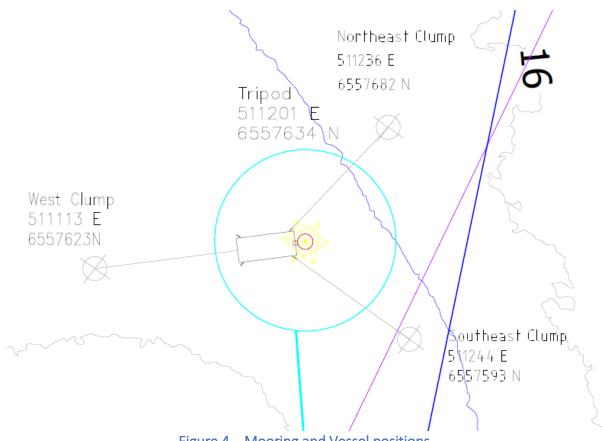


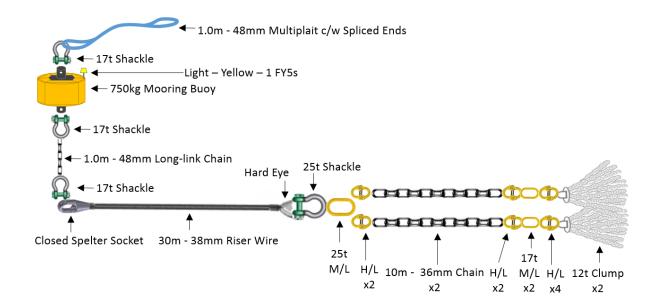
Figure 4 – Mooring and Vessel positions

	EASTING	NORTHING
Target Tripod location	511201	6557634
Northeast Clump Weight	511236	6557682
Southeast Clump Weight	511244	6557593
West Clump Weight	511113	6557623

Table 2 – Mooring Positions



6.5 Mooring Specification



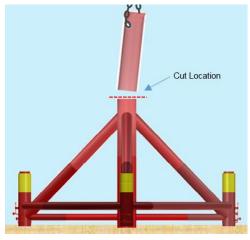


6.6 Tripod Cutting Plan

Due to the complex geometry and varying member weights, the tripod is to be cut in a sequence that will ensure diver safety throughout the operation

Stage 1 Cut – Tower

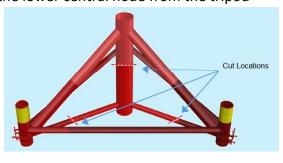
The first stage of the cutting operation will remove approximately 5.8m from the upper part of the central tube





Stage 2 Cut – Lower Central Node

Following removal of the central tower section, the lower central tube will be cut at a position 4.0m from the base, the 3 x \emptyset 508mm horizontal tubes will be cut mid span to completely free the lower central node from the tripod



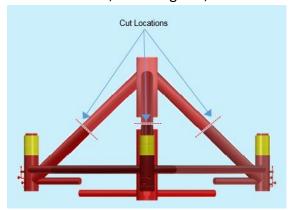


Removal of these sections requires access to the internal region of the tripod and should therefore be performed whilst the frame still retains its structural integrity.



Stage 3 Cut – Diagonal Bracing

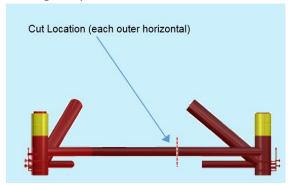
The three grout filled diagonal members will be cut mid span and the upper central node section removed; following this, the lower central node can be removed





<u>Stage 4 Cut – Outer Horizontal Members</u>

The three horizontal members that form the perimeter of the tripod will be cut at a location allowing the piled corners to be recovered individually







6.7 Areas of Interest

Certain areas of interest have been identified for later biofouling analysis typically located at welds and anode entry points; cutting through these locations is to be avoided.

Figures 5 & 6 indicate the areas that are to be avoided when cutting, reds areas are to be avoided, green areas or safe to cut.

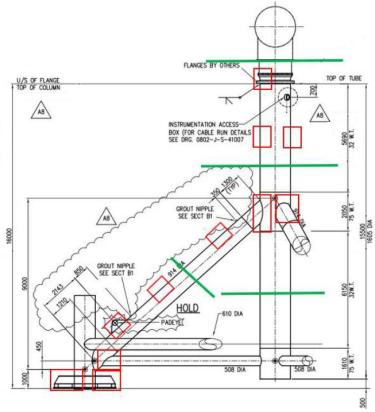


Figure 5 – Areas of Interest

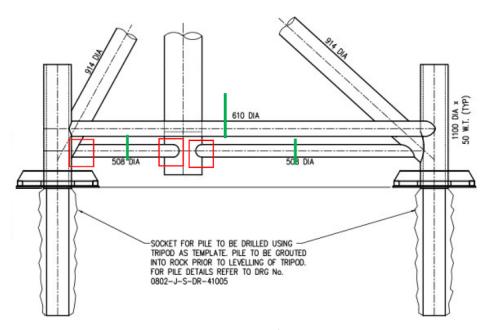


Figure 6 – Areas of Interest



6.8 Equipment List

Equipment	Quantity	Supplied
Moorings		
24t Chain Clumps	3	LM
Hammerlock connection	3	LM
35t Safety Shackle	3	LM
36mm Ground Chain 10m Long	3	LM
38mm Riser Wire 30m	3	LM
25t Safety Shackle	3	LM
750kg Balmoral Float c/w Light	3	LM
12.5t Safety Swivel Hook	3	LM
17t Shackle	3	LM
48mm Eurosteel 150m	3	LM
Other Equipment		
Dive Unit & Equipment	-	LM
Dive Basket	-	LM
Gas	-	LM
Broco Underwater Cutting Gear	-	LM
25t Bow Shackle	1	LM
55t Bow Shackle	1	LM
6.0m EWL Polyester Roundsling – 100t SWL	1	LM

Table 3 – Equipment List



6.9 Deck Layout

The equipment mentioned before will be arranged onto deck as in the picture below.

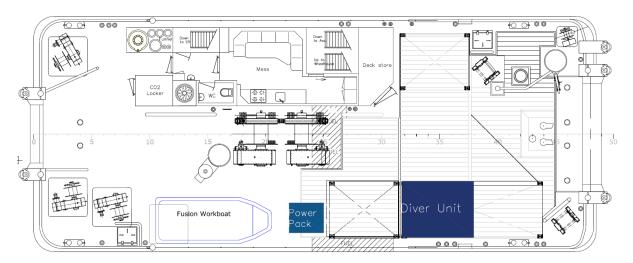


Figure 7 – Deck Layout



7 METHODOLOGY

7.1 Task Summary

No.	TASKS
1.	Equipment Mobilisation & Sail to Site
2.	Stage 1 Cut – Upper Central Tube
3.	Stage 2 Cut – Lower Central Node
4.	Stage 3 Cut – Diagonal Bracing / Upper Node Recovery
5.	Lower Central Node Recovery
6.	Stage 4 Cut – Outer Horizontal Members
7.	Mooring Recovery & Demobilisation



Task #1 Equipment Mobilisation & Sail to Site

	Toolbox Talk	Supervisor Signature and Date
HOLD	Equipment required Equipment Seafastening	

Task 1	Task Summary	Comments	Check	
1.01	Crew to prepare and check the	See Equipment List in Table 3		
	equipment at Leask Marine yard			
1.02	From Hatston Pier, load the equipm	ent on the C-Odyssey using the vessel		
	crane			
1.03	Vessel Master to ensure the boat is stable during operations			
1.04	Crew to seafasten the equipment on the vessel			
1.05	Vessel Master to ensure deck is secure before departing port			
1.06	Vessel to depart from Kirkwall Pier			
1.07	Vessel to sail to Eday	EMEC Permission		
	(07624 345 411) as per Section 3.6			
1.08	Multicat to arrive on site and pick-u	p moorings:		
	Prepare tugger winch with Multiplait rope			
	Pass rope to line-boat crew			
	Line-boat crew to deliver rope end to target mooring buoy			
	Connect rope to mooring buoy			
	Repeat for next moorings (see Table 2 – Mooring Positions)			

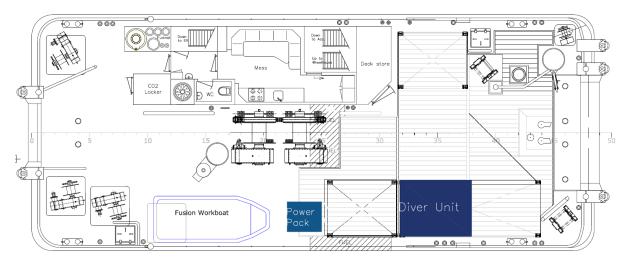


Figure 7 – Deck Layout



Task #2 Stage 1 Cut - Upper Central Tube

	Toolbox Talk	Supervisor Signature and Date
HOLD	1. Broco Cutting	

Task 2	Ta	ask Summary	Check
2.01	•	Main winch wire rigged with 25t shackle and chain strop 25t sling connected to shackle and cable tied to winch wire for later retrieval with crane Rigging overboarded and lowered towards top of tripod Vessel to move as required to ensure that bow roller is directly above	
		centre of tripod	
2.02	•	Diver to enter water and swim to the top of the tripod Diver to burn Ø100mm hole through wall of tubular with Broco gear	
2.03	•	Diver to Feed chain strop through hole and connect to 25t shackle Main winch paid in to take up slack in wire	
2.04	•	Diver to relocate to 1 st cut location and mark approx. 700mm above diagonal tubulars Begin cutting around circumference of tube at marked location, continuous communication between diver and supervisor required	
2.05	•	Diver to advise when last 200mm of cut is approached Ensure that weight of tube is taken by the main winch wire	
2.06	•	Diver to Broco cut final 200mm from a safe location Diver advise when tube has been completely cut and return to surface	
2.07	•	Crew & divers to locate to safe area Pay-in on main winch to lift tubular towards bow roller Retrieve tied off sling and connect to	
		forward crane hook	
2.08	•	Crane to lift tubular section on deck of multicat Deck crew to fasten tubular to deck and release lift rigging & winch wire from tubular	



Task #3 Stage 2 Cut – Lower Central Node

	Toolbox Talk	Supervisor Signature and Date
HOLD	1. Access to internal portion of Tripod	

Task 3	Task Summary Co	omments	Check
3.01	Diver to swim to internal are	ea of tripod with Broco gear	
3.02	base of central tube w	Ensure that cut location does <u>not</u> coincide with weld or anode entry location (see Section 6.7)	
3.03	Once cut on central tube is c Ø508mm horizontal tubes at	omplete, diver to mark each of the three t 5.0m from central tube	
3.04	 Diver to cut each of the Ø508mm tubes Diver check that umbilical is not in a position where it could get trapped when the central node drops When the final cut is almost complete, diver to keep at safe distance in preparation for steel drop Lower central node weight approx. 16.5t 	Cut Locations	
3.05	Diver to return to surface	Section is to be left in place until surrounding sections of tripod have been removed	



Task #4 Stage 3 Cut – Diagonal Bracing Cut / Upper Node Recovery

	Toolbox Talk	Supervisor Signature and Date
HOLD	1. Grout filled members	

Task 4	Ta	sk Summary Comments	Check	
4.01	•	Diver to swim to tripod with Broco gear		
4.02	•	Mark 6.0m from the top of the brace for each of the three diagonal braces Ensure that cut location does not coincide with weld or anode entry location (see Section 6.7)		
4.03	•	Use Broco gear to burn a hole through the central spine for connecting a 55t shackle		
	•	Deck crew to prepare main winch wire with 55t shackle, connect 100t 6.0m EWL Roundsling to shackle and cable tie to winch wire for later retrieval		
	•	wer main winch wire to central spine of tripod, diver connect shackle burned hole		
_	•	Pay-in on main winch wire to take up slack		
4.04	•	Diver to Broco cut through grout filled diagonal brace at marked locations When the final cut is almost complete, diver to keep at safe distance in preparation for steel weight shift		
4.05	•	Diver return to surface, recover all Broco gear on deck		
	•	Pay-in on main winch to lift section towards bow roller (Approx. dry weight 30t)		
4.07	•	Multicat to release its moorings and tow section to Hatston pier (Draft up to 8.0m)		
	•	Upon arrival at Hatston pier, lower section onto seabed and connect onshore crane hook to previously tied off sling Onshore crane to lift section onto pier		



Task #5 Lower Central Node Recovery

	Toolbox Talk	Supervisor Signature and Date
HOLD	1. Grout filled members	

Task 5	Ta	ask Summary Comments	Check
5.01	•	Deck crew to prepare main winch wire with 55t shackle, connect 100t 6.0m EWL Roundsling to shackle and cable tie to winch wire for later retrieval	
F 03	•	Lower main winch wire to central spine of tripod Diver to swim to tripod with Press goar	
5.02	•	Diver to swim to tripod with Broco gear Use Broco gear to burn a hole through the central spine for connecting a 55t shackle Diver to connect 55t shackle to new hole	
5.03	•	Diver return to surface, recover all Broco gear on deck Pay-in on main winch to lift section towards bow roller (Approx. dry weight 16.5t)	
5.04	•	Multicat to release its moorings and tow section to Hatston pier (Draft up to 8.0m) Upon arrival at Hatston pier, lower section onto seabed and connect onshore crane hook to previously tied off sling	
	•	Onshore crane to lift section onto pier	



Task #6 Stage 4 Cut – Outer Horizontal Members

	Toolbox Talk	Supervisor Signature and Date
HOLD	1. Grout filled members	

Task 6	Ta	ask Summary	Comments	Check
6.01	•	Diver to swim to lower half of trip	ood with Broco gear	
6.02	•	Diver to mark location on horizontal member 4.3m from pile leg	Ensure that cut location does <u>not</u> coincide with weld or anode entry location (see Section 6.7)	
6.03	•		ontal member first, the final stage of m the outside of the tripod to ensure	
6.04	•	Repeat Broco cutting process for remaining piles Maintain safe distance from Ensure that care is taken to avoid entrapment when steel section falls away following cutting	r Cut Location (each outer horizontal)	
6.05	•	• •	n wire with 55t shackle, connect 100t and cable tie to winch wire for later ortion of steel section	

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6.06	•	Broco gear to burn a hole through the pile section for connecting a 55t shackle Diver to connect 55t shackle to	A chain strop may be required if the thickness of the piled leg does not allow connection of 55t shackle
6.07	•	new hole Diver return to surface, recover all Broco gear on deck Pay-in on main winch to lift section towards bow roller (Approx. dry weight 20t)	
6.08	•	weight 20t) Multicat to release its moorings and tow section to Hatston pier (Draft up to 8.0m) Upon arrival at Hatston pier, lower section onto seabed and connect onshore crane hook to previously tied off sling Onshore crane to lift section onto pier	
6.09	•	Transit back to Eday Repeat Tasks 6.05 to 6.08 for remaining piled leg sections	



Task #7 Mooring Recovery & Demobilisation

	Toolbox Talk	Supervisor Signature and Date
HOLD		

Task 7	Task Summary Comments	Check		
7.01	Vessel to sail to site			
7.02	Vessel to locate to mooring buoys			
7.03	 C-Odyssey to approach mooring buoy bows on. Buoy and riser recovered to C-Odyssey deck utilising forward crane Chain stopper from 50 t aft winch to be connected to wire riser below swaged fitting Buoy to be disconnected from wire riser, stowed on deck and secured 100 t winch to be connected to riser wire and tensioned Chain stopper from 50 t winch to be disconnected Crew to relocate to safe area Take up on 100 t winch till chain masterlink is below bow roller 12 t chain bundle to be lifted over bow utilising forward crane and landed on deck Chains and buoys to be sea fastened prior to departure from site. 			
7.04	Use the same procedures for all the other mooring lines			
7.05	Once the mooring is Previous Communication Protocol recovered, C-Odyssey to depart the site			
7.06	Vessel to arrive to Kirkwall and onshore crane to demobilise equipment			



8 RISK ASSESSMENT

8.1 Generic Risk Assessment

In the following tables are summarized the Generic Risk Assessment and mitigation measures related to this project.

Vessel Operation

Access routes and working area						
Vessel Access & Egress	TRA VO - 001					
Personnel Transfer	TRA VO - 002					
Personnel Transfer via Man Riding Basket	TRA VO - 003					
Transfer of Equipment between Vessels	TRA VO - 004					
Working Spaces and Location						
Confined Spaces	TRA VO - 011					
Working Overboard	TRA VO - 012					
Working On Deck	TRA VO - 013					
Environmental Conditions						
Working in Darkness	TRA VO - 020					
Sea State	TRA VO - 021					
High Wind Conditions	TRA VO - 022					
Plant & Equipment	Plant & Equipment					
Crane Operations	TRA VO - 031					
Crane operations without Remote Control	TRA VO - 032					
Operational Works						
Anchoring Operations	TRA VO - 050					
Anchor Handling on Deck	TRA VO - 051					
Berthing Operations	TRA VO - 052					
Diving Operations	TRA VO - 054					
Support Boat Launch & Recovery	TRA VO - 055					
Towing Operations	TRA VO - 056					
Other Operations & equipment						
Man Overboard	TRA VO - 081					
Personnel						
Crew New Starts	TRA VO - 100					
Crew Health	TRA VO - 101					

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Diving Operation

	Working Spaces and Location					
Working Area – Quay, Dock, Soffit	TRA DO - 001					
Working over Water	TRA DO - 002					
Stern Gear	TRA DO - 006					
Non-mechanical Environment						
Noise Underwater	TRA DO - 020					
Vibrations Underwater	TRA DO - 021					
Environmental Conditions						
Diving in High Wind Conditions	TRA DO - 031					
Weather Conditions for Diving Operations	TRA DO - 032					
Working in Tidal Conditions	TRA DO - 033					
Plant & Equipment						
Crane Underwater	TRA DO - 040					
Dive Ladder	TRA DO - 041					
Man basket	TRA DO - 048					
Underwater Pneumatic Chainsaw	TRA DO - 049					
Hazardous Materials, Chemicals & Substan	ces					
Charging Cylinders (HP)	TRA DO - 110					
Diving Operations Compressed Air	TRA DO - 111					
Operational Works						
Hot Tapping	TRA DO - 121					
Hydraulic Cable Cutting	TRA DO - 122					
Hydraulic Subsea Drilling Rig	TRA DO - 123					
Underwater Broco Cutting	TRA DO - 126					
Underwater Camera Strobe	TRA DO - 127					
Underwater Camera Strobe Underwater High Pressure (HP) Water Jet	TRA DO - 127 TRA DO - 129					
Underwater High Pressure (HP) Water Jet	TRA DO - 129					
Underwater High Pressure (HP) Water Jet Underwater Jackhammer	TRA DO - 129					
Underwater High Pressure (HP) Water Jet Underwater Jackhammer Manual Handling	TRA DO - 129 TRA DO - 130					
Underwater High Pressure (HP) Water Jet Underwater Jackhammer Manual Handling General	TRA DO - 129 TRA DO - 130 TRA GO - 130					
Underwater High Pressure (HP) Water Jet Underwater Jackhammer Manual Handling General Heavy Loads	TRA DO - 129 TRA DO - 130 TRA GO - 130 TRA GO - 132					
Underwater High Pressure (HP) Water Jet Underwater Jackhammer Manual Handling General Heavy Loads Awkward Loads	TRA DO - 129 TRA DO - 130 TRA GO - 130 TRA GO - 132					
Underwater High Pressure (HP) Water Jet Underwater Jackhammer Manual Handling General Heavy Loads Awkward Loads Operational Works	TRA DO - 129 TRA DO - 130 TRA GO - 130 TRA GO - 132 TRA GO - 133					
Underwater High Pressure (HP) Water Jet Underwater Jackhammer Manual Handling General Heavy Loads Awkward Loads Operational Works Form-working	TRA DO - 129 TRA DO - 130 TRA GO - 130 TRA GO - 132 TRA GO - 133 TRA GO - 140					
Underwater High Pressure (HP) Water Jet Underwater Jackhammer Manual Handling General Heavy Loads Awkward Loads Operational Works Form-working Crane Lifting Operations	TRA DO - 129 TRA DO - 130 TRA GO - 130 TRA GO - 132 TRA GO - 133 TRA GO - 140					
Underwater High Pressure (HP) Water Jet Underwater Jackhammer Manual Handling General Heavy Loads Awkward Loads Operational Works Form-working Crane Lifting Operations Other Operations & equipment	TRA DO - 129 TRA DO - 130 TRA GO - 130 TRA GO - 132 TRA GO - 133 TRA GO - 140 TRA GO - 142					



8.2 Task Specific Risk Assessment

To consult the Task Specific Risk Assessment, please see refer to document *LSK-TGL02-OP3-RA01-R01 - Subsea Tripod Cutting*



9 TOOLBOX TALK BRIEFING

Date/	/20	18				
Project Briefing	Details of P	roject:				
Safety: All PPE to be worn a	at all times				RA No.	
7.III T E to be Worne	at un times					
Site Location	Documenta	cumentation Numbers:			Communications	
		Gener	ic Task Hazards			
☐ Slips, trips	& falls		pped Objects		Manual handling	
☐ Lifting ope			ess on deck			
Entrapmen	it	□ Hot	works		Flammable gases	
☐ Man overb	oard	□ Swi	nging loads		liquids	
□ Working at	height	□ Wir	e / Chains under	tension \Box	Deck operations Visibility	
Attendance Re	cord					
Name (print)	Job		Sign		Date	
Briefing Feedback Remarks: Mitigati				itigation / a	ıdditional	
_				requirements		
Induction / TBT	conducted by	:-	Da	ite:		
-					/2018	
Signed:						



10 CHANGE OF RECORD (MANAGEMENT OF CHANGE)

01	Risk Assessme	nt Review Update		
1.				
Date:	:	Name:	Why?	Sign:
2.		,		
Date:		Name:	Why?	Sign:
3.				
Date:		Name:	Why?	Sign:
02	Method State	ment Revision		
1.				
Date:	:	Name:	Why?	Sign:
2.				
Date:	:	Name:	Why?	Sign:
3.				
Date:		Name:	Why?	Sign:
03	Emergency Pla	n Update		
1.				
Date:		Name:	Why?	Sign:
2.				
Date:	:	Name:	Why?	Sign:



END OF DOCUMENT